

FEATURES



- Fully digital, pressure calibrated and temperature compensated output
- I²C Digital Interface
- Compensated temperature range: -5 to 65°C
- Compound gage and differential pressure configurations
- Insensitive to mounting orientation
- Robust JEDEC SOIC-16 package for automated assembly
- Manufactured according to ISO9001 and ISO/TS 16949 standards
- RoHS & REACH compliant
- Pressure ranges from 10 cmH₂O to 140 cmH₂O (0.14 to 2 PSI)

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DESCRIPTION

The SM9541 Series is a digital, low pressure MEMS sensor family offering state-of-the-art pressure transducer technology and CMOS mixed signal processing technology to produce a digital, fully conditioned, multi-order pressure and temperature compensated sensor in JEDEC standard SOIC-16 package with a dual vertical porting option. It is available in both compound gage or differential pressure configurations. With the dual porting, a vacuum-gage measurement is possible to minimize altitude errors due to changes in ambient pressure.

Combining the pressure sensor with a signal-conditioning ASIC in a single package simplifies the use of advanced silicon micro-machined pressure sensors. The pressure sensor can be mounted directly on a standard printed circuit board and a high level, calibrated pressure signal can be acquired from the digital interface. This eliminates the need for additional circuitry, such as a compensation network or microcontroller containing a custom correction algorithm.

The SM9541 is shipped in sticks or tape & reel.

Medical	Industrial	Consumer
Sleep Apnea	Airflow Measurement	Sports Equipment
CPAP	Pneumatic Gauges	Appliances
Ventilators	Pressure Switches	
Gas Flow Instrumentation	Safety Cabinets	
Air Flow Monitors	Life Sciences	
Negative Pressure Wound Therapy	Gas Flow Instrumentation	

Absolute Maximum Ratings

All parameters are specified at V_{DD} = 3.3 V supply voltage at 25°C, unless otherwise noted.

No.	Characteristic	Symbol	Minimum	Typical	Maximum	Units
1	Supply Voltage	V _{DD}			6.00	V
2	Supply Current	I _{VDD}			4.00	mA
3	Update Period				2	mS
4	Operating Temperature ^(a)	T _{OP}	-5	32	+65	°C
5	Storage Temperature ^(a)	T _{STG}	-40	-	+125	°C
6	Media Compatibility ^(a,b)					

Notes:

a. Tested on a sample basis.

b. Clean, dry gas compatible with wetted materials. Wetted materials include Pyrex glass, silicon, alumina ceramic, epoxy, RTV, gold, aluminum, and nickel.

No.	Product Number	Operating Pressure	Proof Pressure (P _{ROOF}) ^(a,c)	Burst Pressure (P _{ROOF}) ^(a,d)
7	SM9541-010C-S-C-3-S	-0.5 to 10 cmH ₂ O	±1.5 PSI	±3.0 PSI
8	SM9541-010C-D-C-3-S	-10 to 10 cmH ₂ O		
9	SM9541-020C-S-C-3-S	-1 to 20 cmH ₂ O	±4.8 PSI	±6.0 PSI
10	SM9541-020C-D-C-3-S	-1 to 20 cmH ₂ O		
11	SM9541-040C-S-C-3-S	-5 to 40 cmH ₂ O		
12	SM9541-040C-D-C-3-S	-40 to 40 cmH ₂ O		
13	SM9541-060C-S-B-3-S*	-5 to 60 cmH ₂ O		
14	SM9541-100C-S-B-3-S*	-5 to 100 cmH ₂ O	±12 PSI	±15 PSI
15	SM9541-100C-S-C-3-S	-5 to 100 cmH ₂ O		
16	SM9541-100C-D-C-3-S	-100 to 100 cmH ₂ O		
17	SM9541-140C-S-C-3-S	-20 to 140 cmH ₂ O		

Notes:

a. Tested on a sample basis.

c. Proof pressure is defined as the maximum pressure to which the device can be taken and still perform within specifications after returning to the operating pressure range

d. Burst pressure is the pressure at which the device suffers catastrophic failure resulting in pressure loss through the device.

***Prerelease product - The device has not been released to production.**

OPERATING CHARACTERISTICS TABLE

All parameters are specified at V_{DD} = 3.3 V DC supply voltage at 25°C, unless otherwise noted.

Compound Gage						
No.	Characteristic	Symbol	Minimum	Typical	Maximum	Units
18a	Supply Voltage	V _{DD}	3.0	3.3	3.6	V
18b			4.75	5.0	5.25	
19	Pressure Output @ P _{MIN}	OUT _{MIN}		1,638		Counts
20	Pressure Output @ P _{MAX}	OUT _{MAX}		14,745		Counts
21	Full Scale (-0.5 to 10 cmH ₂ O) Span	FSP		13,107		Counts
22	Full Scale (-1 to 20 cmH ₂ O) Span					
23	Full Scale (-5 to 40 cmH ₂ O) Span					
24	Full Scale (-5 to 60 cmH ₂ O) Span					
25	Full Scale (-5 to 100 cmH ₂ O) Span					
26	Full Scale (-20 to +140 cmH ₂ O) Span		-			
27	Resolution			14		Bits
28	Accuracy ^(e,f)	ACC	-1		+1	
29	Compensated Temperature Range	T _{COMP}	-5		+65	°C

Notes:

e. The accuracy specification applies over all operating conditions. This specification includes the combination of linearity, repeatability, and hysteresis errors over pressure, temperature, and voltage.

f. Maximum 10-year zero pressure offset shift < ±2%FS based on 1000 hours of HTOL testing.

Differential						
No.	Characteristic	Symbol	Minimum	Typical	Maximum	Units
30a	Supply Voltage	V _{DD}	3.0	3.3	3.6	V
30b			4.75	5.0	5.25	
31	Pressure Output @ P _{MIN}	OUT _{MIN}		1,638		Counts
32	Pressure Output @ P _{MAX}	OUT _{MAX}		14,745		Counts
33	Full Scale (-10 to 10 cmH ₂ O) Span	FSP		13,107		Counts
34	Full Scale (-20 to 20 cmH ₂ O) Span					
35	Full Scale (-40 to 40 cmH ₂ O) Span					
36	Full Scale (-100 to 100 cmH ₂ O) Span					
37	Resolution			14		Bits
38	Accuracy ^(e,f)	ACC	-1		+1	
39	Compensated Temperature Range	T _{COMP}	-5		+65	°C

Notes:

e. The accuracy specification applies over all operating conditions. This specification includes the combination of linearity, repeatability, and hysteresis errors over pressure, temperature, and voltage.

f. Maximum 10-year zero pressure offset shift < ±2%FS based on 1000 hours of HTOL testing.

SM9541 – I²C Communications

1. SCL Clock frequency:

- 100kHz to 400kHz

2. Slave Address

- The factory setting for the I²C slave address is 28HEX. The part will only respond to the set address.

3. Read Operations

- For read operations, the I²C master command starts with the 7-bit slave address with the 8th bit = 1 (READ). The sensor as the slave sends an acknowledge (ACK) indicating success.
- The sensor has four I²C read commands: Read_DF2, Read_DF3, and Read_DF4. The following figures show the structure of the measurement packet for three of the four I²C read commands, which are further explained below.

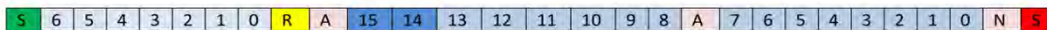
3.1 I²C Read_DF (Data Fetch):

- For the Data Fetch commands, the number of data bytes returned by the sensor is determined by when the master sends the NACK and stop condition.

- For the Read_DF3 data fetch command (Data Fetch 3 Bytes), the sensor returns three bytes in response to the master sending the slave address and the READ bit (1): two bytes of bridge data with the two status bits as the MSBs and then 1 byte of temperature data (8-bit accuracy). After receiving the required number of data bytes, the master sends the NACK and stop condition to terminate the read operation.
- For the Read_DF4 command, the master delays sending the NACK and continues reading an additional final byte to acquire the full corrected 11-bit temperature measurement. In this case, the last 5 bits of the final byte of the packet are undetermined and should be masked off in the application.
- The Read_DF2 command is used if corrected temperature is not required. The master terminates the READ operation after the two bytes of bridge data.

- I²C Read_DF2 – Data Fetch 2 Bytes:

- Slave returns only pressure data to the master in 2 bytes.
- Start Condition – Device Slave Address [6:0] – Read/Write Bit (Read = 1) – Wait for Slave ACK – 2 status bits – 6 pressure bits [13:8] – Master ACK – 8 pressure bits [7:0] – Master NACK – Stop Condition



- I²C Read_DF3 – Data Fetch 3 Bytes:

Slave returns 2 pressure data bytes and temperature high byte [10:3] to the master.

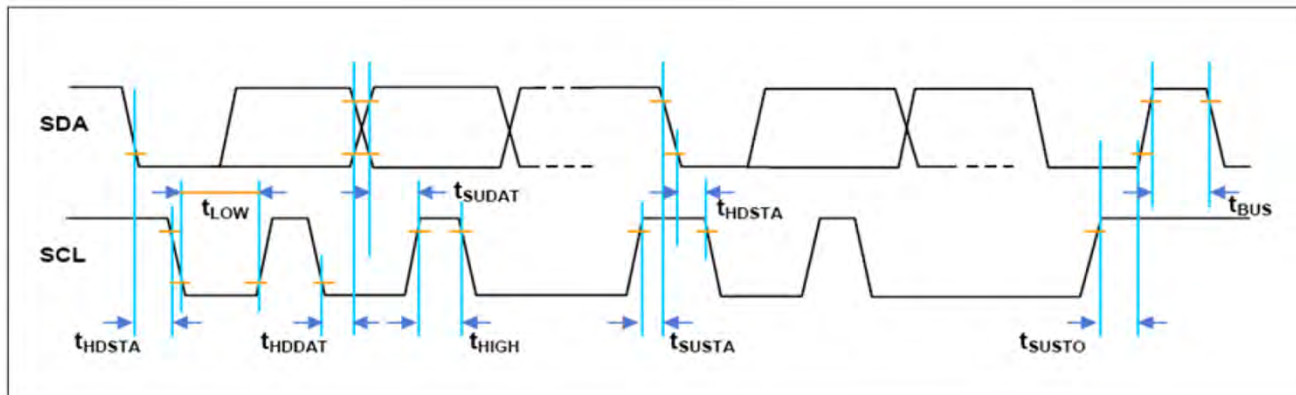
- Start Condition – Device Slave Address [6:0] – Read/Write Bit (Read = 1) – Wait for Slave ACK – 2 status bits – 6 pressure bits [13:8] – Master ACK – 8 pressure bits [7:0] – Master ACK – 8 temperature bits [10:3] – Master NACK – Stop Condition



- I²C Read_DF4 – Data Fetch 4 Bytes:

- Slave returns 2 pressure data bytes and 2 temperature bytes ([10:3] and [2:0]xxxxx) to the master.
- Start Condition – Device Slave Address [6:0] – Read/Write Bit (Read = 1) – Wait for Slave ACK – 2 status bits – 6 pressure bits [13:8] – Master ACK – 8 pressure bits [7:0] – Master ACK – 8 temperature bits [10:3] – Master ACK – 3 temperature bits [2:0] – Master NACK – Stop Condition





Parameter	Symbol	Minimum	Typical	Maximum	Units
SCL Clock Frequency	F _{SCL}	100		400	kHz
Start Condition Hold Time Relative to SCL Edge	t_{HDSTA}	0.1			μs
Minimum SCL Clock Low Width ¹	t_{LOW}	0.6			μs
Minimum SCL Clock High Width ¹	t_{HIGH}	0.6			μs
Start Condition Hold Time Relative to SCL Edge	t_{SUSTA}	0.1			μs
Data Hold Time on SDA Relative to SCL Edge	t_{HDDAT}	0.0			μs
Data Setup Time on SDA Relative to SCL Edge	t_{SUDAT}	0.1			μs
Stop Condition Setup Time on SCL	t_{SUSTO}	0.1			μs
Bus Free Time Between Stop Condition and Start Condition	t_{BUS}	2.0			μs

5. Differences sensor I²C Protocol vs. Original I²C protocol

- **Note: There are three differences in the sensor protocol compared with the original I²C protocol**
- Sending a start-stop condition without any transitions on the CLK line (no clock pulses in between) created a communication error for the next communication, even if the next start condition is correct and the clock pulse is applied. An additional start condition must be sent, which results in restoration of proper communication.
- The restart condition - a falling SDA edge during data transmission when the CLK clock line is still high - creates the same situation. The next communication fails, and an additional start condition must be sent for correct communication.
- A failing SDA edge is not allowed between the start condition and the first rising SCL edge. If using an I²C address with the first bit 0, SDA must be held low from the start condition through the first bit.

6. Diagnostic Features – Status Bits

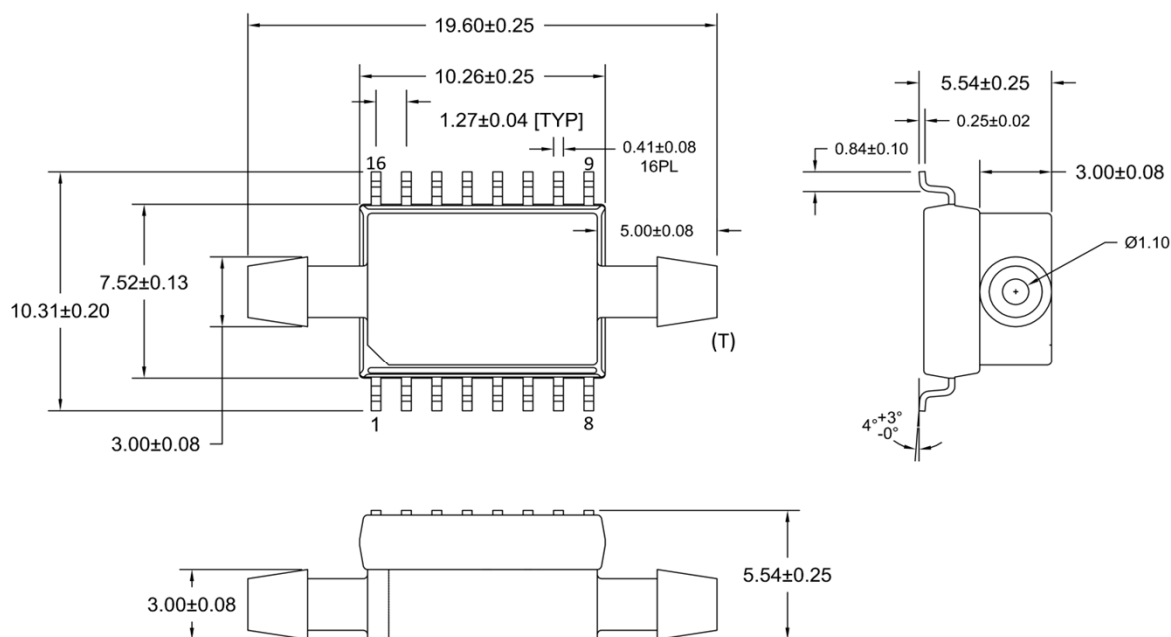
The sensor offers diagnostic features to ensure robust system operation. The diagnostic states are indicated by a transmission of the status of the 2 MSBs of the pressure high byte data.

Status Bits (2 MSBs of Output Packet)	Symbol
00	Normal operation, good data packet
01	Device in Command Mode (not applicable for normal operation)
10 ⁽¹⁾	Stale data: Data that has already been fetched since the last measurement cycle
11	Diagnostic condition exists

Note⁽¹⁾: If a data fetch is performed before or during the first measurement after power-on reset, then “stale” will be returned, but this data is actually invalid because the first measurement has not been completed.

- When the two MSBs are 11, one of the following faults listed below is indicated:
 - Invalid EEPROM signature
 - Loss of bridge positive or negative
 - Bridge input short
 - Loss of bridge source
- All diagnostics are detected in the next measurement cycle and reported in the subsequent data fetch. Once a diagnostic is reported, the diagnostic status bits will not change unless both the cause of the diagnostic is fixed and a power-on-reset is performed.

SOIC-16 Horizontal (B) Package Dimensions



Dimensions are in mm

Qualification Standards

REACH Compliant

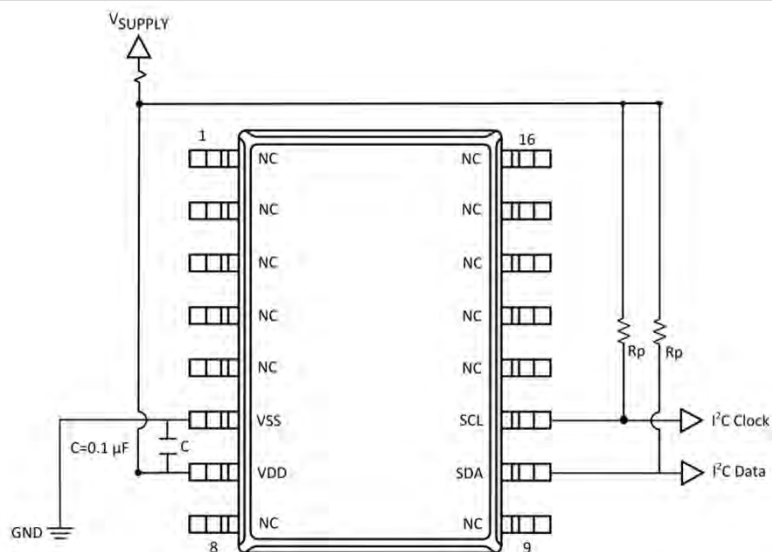
RoHS Compliant

PFOS/PFOA Compliant

For qualification specifications, please contact Sales at sales@si-micro.com



SM9541 + Family Applications Circuit



"C" needs to be in close proximity of the device

Rp = Pull-up Resistors
For Example: 4.7 kΩ Resistors

Package Labeling	
Pin No.	Pin Function
1	NC (No Connect)
2	NC
3	NC
4	NC
5	NC
6	VSS
7	VDD
8	NC
9	NC
10	SDA
11	SCL
12	NC
13	NC
14	NC
15	NC
16	NC

NOTES:

- Do not connect to NC pins

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